

A Level Mathematics Curriculum RoadMap

FINHAM PARK	Year 12			Year 13		
edexcel	Term 1	Term 2	Term 3	Term 4	Term 5	Term 6
bure	 Algebra and Functions: Expressions, equations, quadratics and inequalities. Use of the discriminant. Graphs and Transformations: Trigonometric, reciprocal and polynomial transformed by reflection, translation or stretch. Further Algebra: Factor theorem, polynomial division, binomial expansion, proof Coordinate Geometry: Equations of straight lines and circles, points of intersection. 	 Vectors: Magnitude and direction, resultant vectors, problem solving including distance between two points and bearings. Trigonometry 1: Trigonometric graphs, identities and equations. Differentiation 1: First principals, gradient functions, tangents and normal, stationary points and optimization. Integration: Fundamental theorem of calculus, the power law, area under a curve. 	 Exponentials and Logarithms: Exponential and log graphs and functions, derivative of e^x, laws of logarithms, equations, and modelling growth and decay. Proof: Deduction and contradiction. Algebraic and Partial Fractions: Algebraic division, improper fractions. 	 Sequences and Series: nth term, recurrence relations, sigma notation, formulae for arithmetic and geometric series, modelling. Functions and Modelling: Modulus of a linear function, composite and inverse functions. The Binomial Theorem: Expansion of (a + bx)ⁿ for rational n. Trigonometry 2: Radians, arc length, sector area, identities and equations, double and compound angle formulae, reciprocal and inverse functions. 	 Parametric Equations: Parametric curves and conversion between cartesian and parametric forms, integration and differentiation. Differentiation 2: Trigonometric, exponential, chain, product and quotient rules, differential equations. Numerical Methods: Change of sign, Newton-Raphson method. Integration: Trigonometric, exponential, substitution, by parts, differential equations, trapezium rule. 	 Vectors in 3D: Column vectors, i j and k notation, modelling. Revision
Mechanics	 Quantities and Units in Mechanics: SI units and conversions. Kinematics 1: Graphs of speed, distance, velocity, displacement and time. Constant acceleration (SUVAT) equations and equations of motion. 	 Forces and Newton's Laws: Newton's three laws, equations of motion in 1D or simple 2D, free body diagrams, connected particles. Kinematics 2: Integration and differentiation with acceleration, velocity and displacement. 	• Moments: Simple static contexts, resolving clockwise and anticlockwise and including equations of motion.	 Forces at any Angle: Resolving forces in 2D, friction and limiting equilibrium. Application of Kinematics: Motion under gravity in 2D, projectiles. 	 Application of Forces: Complex systems involving motion in 1D or 2D, connected particles, friction and/or moments with non- parallel coplanar forces. Further Kinematics: Extending constant acceleration (SUVAT) formulae to 2D with vectors, calculus with vectors. 	• Revision
Statistics	 Probability 1: Mutually exclusive and independent events. Statistical Distributions: Discrete probability distributions, binomial distribution. Sampling 	 Data Presentation and Interpretation: Standard deviation, variance, central tendency, statistical diagrams. Statistical Hypothesis Testing: Hypothesis testing in context for binomial distributions. 	 Regression and Correlation: Correlation coefficients in context and hypothesis testing for correlation. Probability 2: Conditional probability using Venn diagrams, tree diagrams and/or two-way tables. 	 The Normal Distribution 1: Understand symmetry, modelling, links to histograms and testing hypothesis. 	• The Normal Distribution 2: Modelling, approximating binomial distribution with a normal, known and unknown variance and/or standard deviation.	• Revision